Application of Wireless Sensor Network to Make Transportation Fleet Information Systems Smart

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ABSTRACT

Traffic signs are tools to control and regulate movement, on streets and crossings. These signs individually play their own essential role in reducing accidents and securing traffic. Unfortunately, thieves steal these signs on suitable occasions to sell them as scrap in black market. Wireless sensor systems are of desirable features including independence, being capable of expanding in remote and inconsistent places. They may be assigned such operations as supervising traffic signs. This essay aims at study of some hierarchical routing protocols or static cluster, introducing a new protocol through which we focus on clustering special nodes having no-battery in contrast to ordinary nodes. The result is to obtain network more stability and optimal energy consumption. The new protocol was tested on real characteristics of more than 600 traffic signs in the city of Hamedan, run in MTALAB software. The findings are examined here.

Keywords: Wireless Sensor Networks, Routing Protocols, Static Clustering, Optimal Energy Consumption, Life Cycle of the Network, MATLAB.

1 INTRODUCTION

To solve social and economic problems that the people around the world face, researchers try to, through such concepts as Smart City Week [1], reach novel approaches to these problems, using new technologies. Smart transportation is one of these efforts. In this regards, we may refer to the application of wireless networks and sensors in providing new urban functions for smart cities a new idea in communication of information in smart cities is digital signs [2].

2 WIRELESS SENSOR NETWORKS

WSN refer to a collection of sensors interconnected a wirelessly and all feel a specific phenomenon. The number of these sensors may be high and their distribution range may be vast. The sensors in these networks may be located manually or distributed randomly in places of interests to function. The main propose of these network, after establishment, is firstly to collects information and secondly to make the life cycle of system as longer as possible [3].

2.1 Tracking Targets

Tracking targets has recently attracted the attention of scientists in operational and research projects. Some of recently experimental projects in field of tracking and supervision are:

- Underwater tracking and surveillance: Aqua nodes [4].
- Border surveillance: Exscal [5].
- System intrusion and recognition projects: line- in the – sand [6][7].
- Moving animals tracking in natural sources: zebraNet protests [8].
- Tracking using video camera: Mesh Eyes, Cyclops – Sens Eye [9][10][11].

The issue of tracking in WSN may be defined as a network of "n" wireless sensor nodes formed to track targets in a region. "M" targets are located in this region. Sampling signals transmitted for
targets (chemicals, vibrations, audio signals), these sensing nodes recognize them or their absence. In view of processing and formation of network structure, algorithms may be categorized into two distributed and concentrated ones. Under the latter method, one node (or a central entity) obtains information from the whole network (assuming that the transmission of information from all modes to this central node). Then, the optimal structure (cluster of tree) is formed on the basis of cross-network data. By cluster-based method, a cluster is made of nodes before the setting up of the net (static) or at the same time as the target is recognized (dynamic) [12][13]. The group head (cluster head) is determined. The nodes send their data on the target is the related cluster head [14]. The cluster head locates the target after collection of data, sending the concerned report to sink node [15], based on tree method, similar to methods based on cluster, and before the start of network's operation or as soon as the recognition of target. The tree-structure is made of nodes; each mode sends its information to the parent node. The collection of data to the root node. The target is located and related report is sent by the root to the sink. Under the hierarchical routing methods (based on clustering) [16][17][18][19]. The modes may process and transmit to more vigorously while nodes may be used to perform the sensing function in vicinity of the target, consuming low level of energy. In fact, the hierarchical method, forming clusters are allocating special duties to cluster heads, may greatly contribute to life cycle, energy efficiency of system and comparability, avoiding single-cross architecture. The hierarchical routing is a basis for less energy demand of a cluster, through aggregation and combination of data to reduce the number of sent messages. Hierarchical routing was mostly two-layer routing, one of which is used to select the cluster head and the other is allocated the duty to routing. However, the most of technologies are not related to routing, they speak of who and when the process or aggregation of data, or allocation of channels [20].

3 ROUTING PROTOCOL

3.1 LEACH

This protocol is one of the most famous hierarchical protocols for WSN (Figure 1) [21].

Under this protocol, the time is divided into equal turns. Each turn is divided into two phases. The second phase is related to the ordinary function of the network, named stable phase. In the first phase, based on comparison probability function CH is chose. (Figure 2). The choice of CH is made in this way that each sensing node chooses a number between one and zero in case this number is less than a fixed threshold. That node is chosen as CH in that turn. This probability function has been selected in such a way that each node is selected as CH once per determined number turns.

By doing so, the consumption of energy is distributed over the net. Following the selection of CHs in the commissioning phase of each turn, each CH informs other modes of its selection. Each mode selects its appropriate CH for itself. This fact is notified to relate CH. As result, clusters are formed.

At the next step, each CH provides its clusters modes with time planning, allocating each sensor a phase to avoid the collision among data of sensors in each cluster [22].

![](image)

**Fig. 1. LEACH protocol with cluster nodes**

\[ T(n) = \frac{p}{1 - p \cdot \left( r \mod \frac{1}{p} \right)} \text{ if } n \in G \]

**Fig. 2. LEACH possibility of implementing**

3.2 SEP

SEP is one of hierarchical protocols for wireless network, suitable for heterogeneous environments respect to the energy. We also assume that these sensors are not randomly distributed but the selection of cluster head are based on the imbalance of energy in the network [23].

**Solution:**

Selection of two parameters of PAdv and PNM. Each node knows all energy of the network, they respectively refer to the probability for being cluster head for normal and power – holding modes assuming.

3.2.1 Properties of SEP

- Its energy consumption is balanced
The probability for choosing power–holding modes to be chosen as cluster head is high.

- The life cycle of the net is high.
- It is comparable and dynamic.

\[ n \times (1 - m) \times P_{nrm} + n \times m \times P_{adv} = n \times P_{opt} \]

Fig. 3. The number of cluster heads in each round in heterogeneous environments

Averagely, the number of cluster head is chosen on the basis of the formula reflected in the (Figure 3).

\[ P_{nrm} = \frac{P_{opt}}{1 + \infty \times m} \]

\[ P_{adv} = \frac{P_{opt}}{1 + \infty \times m} \times (1 + \infty) \]

Fig. 4. Weight probability

The weight probability for ordinary and special nodes are \( P_{adv} \) and \( P_{nrm} \) respectively.

\[ T(S_{nrm}) = \frac{P_{nrm}}{1 - P_{nrm} \times (r \mod \frac{1}{P_{nrm}})} \]

\[ T(S_{adv}) = \frac{P_{adv}}{1 - P_{adv} \times (r \mod \frac{1}{P_{adv}})} \]

\[ 0 \quad \text{otherwise} \]

Fig. 5. Threshold

The selection of threshold for power–holding nodes are reflected in (Figure 5).

3.2.2 Comparison with LEACH

- Complete consumption of additional energy in power-holding node.
- Longer life cycle is 26% higher than that of LEACH.

4 NEW ROUTING PROTOCOL (SNN)

All existing routing protocols under heterogeneous environment try to meet the balance in the selection of cluster head among special and ordinary cluster heads. This happens with the probability function of selecting in each group. This algorithm tries to take another probability in addition to previous cases. These probabilities are to take into consideration of special and ordinary clusters for candidate cluster heads from ordinary modes.

The algorithm of SNN selects the cluster head among ordinary nodes in line with (Formula 2).

\[ S(i).ENERGY = 0 \quad \&\& \quad booln = true \quad \&\& \quad booln2 = true \quad \&\& \quad temp\_rand <= (p_{nrm}*2 / (1 - p_{nrm} \times \mod(r, \text{round}(1/p_{nrm})))) \]

Formula 2

\[ S(i) = \text{number of arrange among ordinary nodes}; \]

\[ \text{booln}= \text{Boolean variables}. \]

\[ (\text{temp}\_\text{rand})= \text{a numerical variable between 0 and 1}. \]

SNN chooses ordinary cluster head based on adjusting sensing range.

The adjustment of sensing range is a parameter based on which an ordinary node fixed the change to be selected as cluster head. This parameter should be of distance with less than meter between ordinary node of the candidate cluster head and specific cluster head. Also, this parameter should be in a distance less than one-meters between ordinary node (candidate cluster head) and ordinary one. Figures 4 and 5 show a sensing range.

5 PROCESS OF DATA TRANSMISSION

The data transmission may be performed 3 groups of nodes

1) Ordinary nodes
2) Ordinary cluster head
3) Special (cluster head)
4) Ordinary nodes send their data to the neighboring cluster head node. The head may be either ordinary or special.
In next section Figure 6 shows the distribution of these under the case study ordinary cluster nodes sends its own data or the data sent to it by a member to neighboring cluster to the special cluster head nodes in a shower manner. Figures 6 and 7 show the flow of data in WSN.

6 IMPLEMENTATION

![Fig. 6. Transmission of ordinary node with ordinary cluster head](image)

**Fig. 6. Transmission of ordinary node with ordinary cluster head**

**Fig. 7. find the nearest cluster head by the cluster-heads for ordinary**

![Formula 3 Calculate the Euclidian distance](image)

**Formula 3 Calculate the Euclidian distance**

\[ D(i, j) = \sqrt{A^2 + B^2} = \sqrt{(X_{i1} - X_{j1})^2 + (X_{i2} - X_{j2})^2}. \]

6.1 Simulation

SNN clustering sensing radius '1' of Figure 9 shows. Featured cluster head node is red and green cluster head nodes are normal.

![Fig. 9. sensing radius '1'](image)

**Fig. 9. sensing radius '1'**

SNN clustering sensing radius '4' of Figure 10 shows. Featured cluster head node is red and green cluster head nodes are normal.

![Fig. 10. sensing radius '4'](image)

**Fig. 10. sensing radius '4'**

SNN clustering sensing radius '5' of Figure 11 shows. Featured cluster head node is red and green cluster head nodes are normal.
6.2 Comparison of two methods for the selection of cluster heads energy consumption

Figure 12 compares the energy consumption patterns in the data by a typical cluster head node is the destination Sink. The red graph nodes and ordinary cluster head to the nearest cluster head node, especially for broadcast delivery. The blue Graphs has a normal cluster heads his own and delivers energy from the battery to the SINK. However, calculating the energy consumption among cluster heads of special flood the nature of the message protocol is compromise.

6.3 The results of a comparison of three methods of energy SNN Clustering

Figure 13 SNN protocol with three other protocols in terms of energy consumption shows.

7 REFERENCES


